

For the finiteness result, we define $u = \sum_{i=1}^n (e_i/P_i)$, $d_{\max} = \max_{1 \leq i \leq n} \{d_i\}$ and $P = \text{lcm}(P_1, \dots, P_n)$. Define $h_T(t)$ to be the sum of the execution times of all the tasks in set T whose absolute deadlines are less than or equal to t .

Theorem 3.12. A task set of n tasks is not EDF-feasible iff

- $u > 1$ or
- there exists

$$t < \min \left\{ P + d_{\max}, \frac{u}{1-u} \max_{1 \leq i \leq n} \{P_i - d_i\} \right\}$$

such that $h_T(t) > t$.

Under this theorem, we only need to check for feasibility up to some finite time. We can build the proof of Theorem 3.12 using the following series of lemmas.

Lemma 3.9. A given set T of periodic tasks is not EDF-schedulable iff there exists some time t such that $h_T(t) > t$.

Proof. This has been left to the reader.

Lemma 3.10. Given a set T of n periodic tasks, if $u \leq 1$,

$$h_T(t + P) > t + P \Rightarrow h_T(t) > t \quad \text{for all } t \geq d_{\max}$$

Proof

$$\begin{aligned} h_T(t) + P &= \sum_{i=1}^n e_i \left(\left\lfloor \frac{t - d_i}{P_i} \right\rfloor + 1 \right) + P \\ &\geq \sum_{i=1}^n e_i \left(\left\lfloor \frac{t - d_i}{P_i} \right\rfloor + 1 \right) + P \sum_{i=1}^n \frac{e_i}{P_i} \\ &= \sum_{i=1}^n e_i \left(\left\lfloor \frac{t - d_i + P}{P_i} \right\rfloor + 1 \right) && \text{since } P \text{ is a multiple of } P_i \\ &= h_T(t + P) \end{aligned}$$

Hence,

$$h_T(t + P) > t + P \Rightarrow h_T(t) > t \tag{3.54}$$

Q.E.D.

Lemma 3.11. If task set T is not EDF-feasible and $u \leq 1$, then there exists $t < P + d_{\max}$ such that $h_T(t) > t$.

Proof. Follows immediately from Lemma 3.10.

Q.E.D.

Lemma 3.12. Suppose T is not feasible and $u \leq 1$. Then $h_T(t) > t$ implies

$$t < d_{\max} \quad \text{or} \quad t < \max_{1 \leq i \leq n} \{P_i - d_i\} \frac{u}{1 - u}$$

Proof. Suppose that $t > d_{\max}$. We have

$$\begin{aligned} h_T(t) &\leq \sum_{i=1}^n e_i \frac{t - d_i + P_i}{P_i} \\ &= t \sum_{i=1}^n \frac{e_i}{P_i} + \sum_{i=1}^n \frac{P_i - d_i}{P_i} \\ &\leq \sum_{i=1}^n \left[\frac{e_i}{P_i} \left(t + \max_{1 \leq i \leq n} \{P_i - d_i\} \right) \right] \end{aligned} \quad (3.55)$$

If $h_T(t) > t$, we will have from (3.55),

$$\begin{aligned} t &< \sum_{i=1}^n \frac{e_i}{P_i} \left(t + \max_{1 \leq i \leq n} \{P_i - d_i\} \right) \\ \Rightarrow t &< \max_{1 \leq i \leq n} \{P_i - d_i\} \frac{u}{1 - u} \end{aligned} \quad (3.56)$$

Q.E.D.

3.2.3 Allowing for Precedence and Exclusion Conditions*

We have assumed in the above sections that tasks are independent and are always preemptible by other tasks. We will now relax both these assumptions and present several scheduling heuristics.

Consider a set of tasks with a precedence graph, which are released at time 0. A deadline is specified for each task. It is assumed that the deadlines are chosen so that even if a task completes at its deadline, there will be enough time to execute its children in the task graph by their deadlines. If all the tasks that form a task graph are assigned to the same processor, then we can use the algorithm in Figure 3.19.

Example 3.21. Consider the task graph shown in Figure 3.20a, where the task execution times and deadlines are as follows:

Task T_i	e_i	d_i	Task T_i	e_i	D_i
1	3	6	2	3	7
3	2	20	4	5	21
5	6	27	6	6	28